# Inference of polynomial invariants for imperative programs [Cachera+, SAS12]

Kohei Asano

### What I did in the undergraduate.

# Create a poster that summarize Cacheras' work[SAS12] Implement it in Rust from almost scratch

# $\rightarrow$ In this presentation, I presents summary of Cacheras' work[SAS12], and introduce few related work.



## Summary of Cachera et al., [SAS12]

#### + Presents a sound method of computing polynomial equality invariants for imperative programs

Syntax is restricted to polynomial (dis)equality conditions and assignments.

#### Presents a fast polynomial invariant inference method

Output: Polynomial equality invariants at the end of a program(post condition)  $tg - t_0g + v - v_0 = 0$  $x_0 tg - x_0 t_0 g + x_0 v - x_0 v_0 = 0$ 







### Table of Contents

#### Kerview Motivation and Overview

#### Semantics

#### Fast inference of invariants

#### Related work



4

### Table of Contents

### Motivation and Overview

- Motivation and Definition for polynomial invariant
- Overview of polynomial invariant computation in this work



#### Fast inference of invariants





### What are invariants good for?

#### Safety Verification, Termination Analysis

1 
$$x = x0; v = v0; t = t0;$$
  
2 while  $(t - t1) != 0$  do {  
3  $x = x + v * dt;$   
4  $v = v - g * dt;$   
5  $t = t + dt;$   
6 }  
7 assert( $t * g - t_0 * g + v - v_0 == 0$ );  $\rightarrow$  The



#### his assertion never fails, because

 $tg - t_0g + v - v_0 = 0$  is invariant at location  $l_7$  (line 7).



### What are invariants good for?

#### Safety Verification, Termination Analysis

1 
$$x = x0; v = v0; t = t0;$$
  
2 while  $(t - t1) != 0$  do {  
3  $x = x + v * dt;$   
4  $v = v - g * dt;$   
5  $t = t + dt;$   
6 }  
7 assert( $t * g - t_0 * g + v - v_0 == 0$ );

#### (inequality invariants) Inferring Complexity bounds [Breck+ POPL20]

```
int subsetSumAux(int * A, int i, int n, int sum) {
   nTicks++;
                 auxiliary variable
   if (i \ge n) {
       if (sum == 0) { found = true; }
       return 0;
   int size = subsetSumAux(A, i + 1, n, sum + A[i]);
   if (found) { return size + 1; }
   size = subsetSumAux(A, i + 1, n, sum);
   return size;
```

- This assertion never fails,

$$\begin{array}{l} \mathsf{nTicks}' \leq \mathsf{nTicks} + 2^h - 1 \ \land \ \mathsf{return}' \leq h - 1 \ \land \\ h \leq \max(1, 1 + \mathsf{n} - \mathsf{i}) \end{array}$$

 $\rightarrow$  This function call takes exponential time in n in the worst case.



### Definition of Polynomial invariant

In this slides  $\mathbb{R}^m$  represents all of program states.  $\neq$  (First-order) Assertion  $\varphi$ , which doesn't contain any quantifiers, is **Invariant at location** l

:  $\iff \varphi$  is true whatever program state reaching at *l*.



hing at l.
1 x = x0; v = v0; t = t0;
2 while (t - t1) != 0 do {
3 x = x + v \* dt;
4 v = v - g \* dt;
5 t = t + dt;
6 }
7 assert( t \* g - t\_0 \* g + v - v\_0 == 0 );

 $tg - t_0g + v - v_0 = 0$  is an invariant at location  $l_7$  (line 7).





### Definition of Polynomial invariant

In this slides  $\mathbb{R}^m$  represents all of program states.  $\neq$  (First-order) Assertion  $\varphi$ , which doesn't contain any quantifiers, is **Invariant at location** l

 $: \iff \varphi$  is true whatever program state reaching at l.

 $\neq \varphi$  is polynomial (equality) invariant at l assert(  $t * g - t_0 * g + v - v_0 == 0$ ); :  $\Leftrightarrow$  Invariant  $\varphi$  at location *l* can be written as  $tg - t_0g + v - v_0 = 0$  is an invariant at location  $l_7$  (line 7).  $\varphi(x_1, \dots, x_m) = \bigwedge_i p_i(x_1, \dots, x_m) = 0$   $p_i \in \mathbb{R}[x_1, \dots, x_m], x_1, \dots, x_m$  are program variables

Invariants can be seen as any over-approximations of reachable sets, polynomial invariants can be seen as any over-approximations of reachable sets by ideals.  $\approx$  Equation systems

x = x0; v = v0; t = t0;2 while  $(t - t1) != 0 do {$ x = x + v \* dt;v = v - g \* dt;t = t + dt;





# Approximation by Ideal Domain

# This work uses **Abstract Interpretation on Ideal Domain** based on following **Galois Connection** to compute polynomial invariant.





Define Concrete Weakest Precondition Predicate **Transformer**(WPPT) $B^{\nu}[c]$  and **Abstract WPPT**  $[c]^{\sharp}$ to ensure  $\gamma(\llbracket c \rrbracket^{\sharp}\langle g \rangle) \subseteq B^{\nu}\llbracket c \rrbracket\gamma\langle g \rangle$ 

- 1. Generate fixed degree **Generic Template**  $\langle g \rangle$  and compute WP  $[c]^{\sharp}(g)$  in Abstract Domain
- 2. Solve a constraint  $[c]^{\sharp}\langle g \rangle \equiv \langle 0 \rangle$  and  $\gamma([c]^{\sharp}\langle g \rangle) \subseteq B^{\nu}[c]_{\gamma}\langle g \rangle$  ensure g = 0 is a polynomial invariant.



### Define Concrete and Abstract Weakest Precondition Predicate **Transformer**(WPPT) to ensure $\gamma(\llbracket c \rrbracket^{\sharp} \langle g \rangle) \subseteq B^{\nu} \llbracket c \rrbracket \gamma \langle g \rangle$



Abstract Domain: *I* 

- $B^{\nu}[c]$ : Concrete WPPT
  - [c]<sup> $\ddagger$ </sup>: Abstract WPPT









1. Generate fixed degree **Generic Template**  $\langle g \rangle$  and compute WP[[c]]<sup>#</sup> $\langle g \rangle$ in Abstract Domain











a polynomial invariant.





Abstract Domain:  $\mathcal{I}$ 

2. Solve a constraint  $[c]^{\sharp}\langle g \rangle \equiv \langle 0 \rangle$  and  $\gamma([c]^{\sharp}\langle g \rangle) \subseteq B^{\nu}[c] \gamma \langle g \rangle$  ensure g = 0 is

 $B^{\nu} \llbracket c \rrbracket$ : Concrete WPPT  $\llbracket c \rrbracket^{\sharp}$ : Abstract WPPT  $\llbracket c \rrbracket^{\sharp} \langle g \rangle \not\equiv \langle 0 \rangle$  $\llbracket c \rrbracket^{\sharp}$  $\llbracket c \rrbracket^{\sharp} \langle g \rangle = \langle 0 \rangle \implies \gamma(\langle 0 \rangle) = \mathbb{R}^m \subseteq B^{\nu} \llbracket c \rrbracket \gamma(\langle g \rangle) = \mathbb{R}^m \text{ and }$  $B^{\nu}[\![c]\!]\gamma(\langle g \rangle) = \mathbb{R}^m \implies g = 0$  is polynomial invariant



) = 0

14

### Table of Contents

#### Motivation and Overview

#### Semantics

- Syntax, Operational Semantics
- WPPT(Weakest Precondition predicate transformer), Abstract WPPT
- Correctness

#### Fast inference of invariants

#### Related work



and assignments

- A variant of Language IMP[Winskel, 1993]
- No functions

$$p \in \mathbb{R}[\mathbf{x}_1, \dots, \mathbf{x}_m]$$

$$\mathbb{V} \ni var ::= \mathbf{x}_1 | \dots | \mathbf{x}_m$$

$$\mathbb{T} \ni test ::= p \bowtie 0$$

$$\mathbb{P} \ni c ::= var := p$$

$$| c ; c$$

$$| if test the$$

$$| while test$$

$$| skip$$



#### + The imperative language syntax of which is restricted to polynomial guards

polynomials

program variables

polynomial guards

polynomial assignments sequence

en c else c conditional structure do cloop structure skip assertion

where  $\bowtie$  stands for = or  $\neq$ . We will also use  $\bowtie$  for the negation of  $\bowtie$ .



### **Operational Semantics**

#### Standard Operational Semantics

**Notation:** given  $\sigma = (\sigma_1, \ldots, \sigma_m)$ , we note  $\sigma[v]_j$  the updated state  $(\sigma_1,\ldots,\sigma_{j-1},v,\sigma_{j+1},\ldots,\sigma_m).$ 

 $\begin{array}{c} eq & \frac{\sigma \rightarrow \sigma'}{\langle c, \sigma \rangle \rightarrow \langle c, \sigma' \rangle} \end{array} congruence \end{array}$  $\frac{p(\sigma) = v}{\langle \mathbf{x}_{j} := p, \sigma \rangle \to \sigma[v]_{j}} assign$  $\frac{1}{2} \frac{\partial f}{\partial c_1, \sigma} if \qquad where \qquad \begin{array}{c} 0 = 0 \\ v \neq 0 \end{array} \right\} \equiv true$  $\frac{1}{2} \langle c_2, \sigma \rangle \quad if \quad where \quad \begin{cases} 0 \neq 0 \\ v = 0 \end{cases} \\ v = 0 \end{cases} \equiv false$ n  $(c; \mathbf{while} \ b \ \mathbf{do} \ c) \ \mathbf{else} \ \mathbf{skip}, \sigma$  while



### Concrete WPPT (Weakest Precondition Predicate Transformer)

### Compute Weakest (liberal) precondition from program c and post-condition S.

 $B^{\nu}[\![\mathbf{x}_{i} := p]\!] S = \{x \in \mathbb{R}^{m} \mid x[p(x)]\}$ where  $x[p(x)]_i$  is the element  $(x_1,$  $B^{\nu}[skip] S = S$  $B^{\nu}[c_1; c_2] S = B^{\nu}[c_1] (B^{\nu}[c_2] S)$  $B^{\nu}[[if \ p \bowtie 0 \ then \ c_1 \ else \ c_2]] \ S = (B^{\nu}[[c_1]] \ S \cap [[p \bowtie 0]]) \cup (B^{\nu}[[c_2]] \ S \cap [[p \bowtie 0]]))$ where  $\llbracket p \bowtie 0 \rrbracket = \{x \in \mathbb{R}^m \mid p(x) \bowtie 0\}$  $B^{\nu}[while \ p \bowtie 0 \ do \ c] \ S = \nu F_{c,p,S}$  Greatest fix point operator induce partial correctness where  $F_{c,p,S} = \lambda X.(\llbracket p \bowtie 0 \rrbracket \cap S) \bigcup (\llbracket p \bowtie 0 \rrbracket \cap B^{\nu} \llbracket c \rrbracket X)$ 

 $B^{\nu}\llbracket c\rrbracket : \mathcal{P}(\mathbb{R}^m) \to \mathcal{P}(\mathbb{R}^m)$ 

$$j \in S$$
}  
...,  $x_{j-1}, p(x), x_{j+1}, ..., x_m$ )







### Example of Concrete WPPT Computation

c := while x - 1 != 0 do x := x + 1; $B^{\nu}[\![c]\!]\{1\}$ 

where  $F = \lambda X.([x - 1 = 0] \cap \{1\}) \cup ([x - 1 \neq 0] \cap B^{\nu}[x := x + 1]]X)$  $= \nu F$ 

 $=\mathbb{R}$ 

 $\rightarrow$  partial correctness { $x \in \mathbb{R}$  } c {x = 1 }



### Example of Concrete WPPT Computation

c := while x - 1 != 0 do x := x + 1; $B^{\nu}[c]{1}$ 

- where  $F = \lambda X.([x 1 = 0]] \cap \{1\}) \cup ([x 1 \neq 0]] \cap B^{\nu}[x := x + 1]]X$  $= \nu F$
- $=\mathbb{R}$

Generally,  $\sigma \in B^{\nu} \llbracket c \rrbracket S \Rightarrow \begin{cases} \exists \sigma_f \in S, \\ \text{or} \end{cases}$ 

 $\rightarrow$  partial correctness { $x \in \mathbb{R}$  } c {x = 1 }

$$\begin{array}{l} \langle c,\sigma\rangle \to^+ \sigma_f \\ \langle c,\sigma\rangle \to^\infty \end{array}$$
 holds.



### Example of Concrete WPPT Computation

c := while x - 1 != 0 do x := x + 1; $B^{\nu}[c]{1}$ 

- $= \nu F$  where  $F = \lambda X.([x 1 = 0]] \cap \{1\}) \cup ([x 1]) \cup ([x 1$
- $=\mathbb{R}$

Generally,  $\sigma \in B^{\nu} \llbracket c \rrbracket S \Rightarrow \begin{cases} \exists \sigma_f \in S, \\ \text{or} \end{cases}$ 

 $B^{\mu}[\![c]\!]\{1\}$ 

 $= \mu F$ 

 $= \{1, 0, -1, -2, \cdots\}$ 

$$x - 1 \neq 0 ]] \cap B^{\nu} [x := x + 1] X)$$

 $\rightarrow$  partial correctness { $x \in \mathbb{R}$  } c {x = 1 }

$$\begin{array}{l} \langle c,\sigma\rangle \to^+ \sigma_f \\ \langle c,\sigma\rangle \to^\infty \end{array}$$
 holds.

#### $\rightarrow$ total correctness[ $x \in \mathbb{Z} \land x \leq 1$ ]c[x = 1]



### Abstract WPPT

#### Compute Polynomial Weakest precondition from program c and polynomial post-condition I.

$$\begin{split} \llbracket \mathbf{x}_{j} &:= p \rrbracket^{\sharp} I = \langle \{q[\mathbf{x}_{j} \mapsto p], q \in I\} \rangle \\ \llbracket \mathbf{s} \mathbf{k} \mathbf{i} p \rrbracket^{\sharp} I = I \\ \llbracket s_{1}; s_{2} \rrbracket^{\sharp} I = \llbracket s_{1} \rrbracket^{\sharp} (\llbracket s_{2} \rrbracket^{\sharp} I) \\ \llbracket \mathbf{i} f p \neq 0 \text{ then } c_{1} \text{ else } c_{2} \rrbracket^{\sharp} I = p \cdot (\llbracket c_{1} \rrbracket^{\sharp} I) \sqcap^{\sharp} \operatorname{Rem}(\llbracket c_{1} \rrbracket^{\sharp} I) \sqcap^{\sharp} \operatorname{Rem}(\llbracket c_{2} \rrbracket^{\sharp} I) \amalg^{\sharp} I = \nu(F_{c,p,I}^{\sharp}) \\ \text{where } F_{c,p,I}^{\sharp} = \lambda J. \ p \cdot (\llbracket c_{1} \rrbracket^{\sharp} J) \sqcap^{\sharp} \operatorname{Rem}(I, p) \\ \llbracket \mathbf{w} \mathbf{h} \mathbf{h} \mathbf{h} p = 0 \ \mathbf{d} \mathbf{h} c_{1} = \nu(\overline{F}_{c,p,I}^{\sharp}) \\ \text{where } \overline{F}_{c,p,I}^{\sharp} = \lambda J. \ p \cdot I \sqcap^{\sharp} \operatorname{Rem}(\llbracket c_{1} \rrbracket^{\sharp} J, p) \end{split}$$

 $I \sqcap^{\sharp} J$ : an ideal generated by sum of I and J's generator  $\operatorname{Rem}(I,p)$ : an ideal generated by **remainders** when I's generators are divided by p.

 $\llbracket c \rrbracket^{\sharp} : \mathcal{I} \to \mathcal{I}$ 

#### $\gamma(\llbracket c \rrbracket^{\sharp} \langle g \rangle) \subseteq B^{\nu} \llbracket c \rrbracket \gamma(\langle g \rangle)$

 $\mathbb{Z}_2 ]$ <sup> $\sharp I, p)</sup></sup>$  $[1]^{\sharp}I, p$ 





### Example of Computing Abstract WPPT

$$\neq$$
 Interpretation of  $P := if x - y = 0$  then

# Abstract Domain $\llbracket P \rrbracket^{\sharp} \langle x - 1, y - 2 \rangle$ $= \langle x - y \rangle \cdot \langle x, y - 2 \rangle \sqcap^{\sharp} \operatorname{Rem}(\langle (x - 1, y - 1) \rangle, x - y)$ $\operatorname{Rem}(f, p): \text{ Graded reverses}$

$$= \left\langle x^2 - xy, xy - y^2 - 2x + 2y \right\rangle \sqcap^{\sharp} \left\langle y - 1 \right\rangle$$

$$=\left\langle x^{2}-xy,xy-y^{2}-2x+2y,y-1\right\rangle$$

x := x + 1; else y := x + 1;

Rem(*f*,*p*): Graded reverse lexicographical order



### Example of Computing Abstract WPPT

 $\neq$  Interpretation of P := if x - y = 0 then x := x + 1; else y := x + 1;

Abstract Domain $\llbracket P \rrbracket^{\sharp} \langle x - 1, y - 2 \rangle$  $= \langle x - y \rangle \cdot \langle x, y - 2 \rangle \sqcap^{\sharp} \operatorname{Rem}(\langle (x - 1, y - 1 \rangle, x - y))$ <br/>Rem(f, p): Graded reverse lexicographical order

$$= \left\langle x^2 - xy, xy - y^2 - 2x + 2y \right\rangle \sqcap^{\sharp} \left\langle y - 1 \right\rangle$$

$$\gamma(\langle x-1, y-2 \rangle) = \{(1,2)\}$$

$$\gamma(\left\langle x^2-xy,xy-y^2-2x+2y,y-1\right\rangle)=\{($$

 $(1,1)\}$ 



### Example of Computing Abstract WPPT

 $\neq$  Interpretation of P := if x - y = 0 then x := x + 1; else y := x + 1;

**Abstract Domain**  $\llbracket P \rrbracket^{\sharp} \langle x - 1, y - 2 \rangle$  $= \langle x - y \rangle \cdot \langle x, y - 2 \rangle \sqcap^{\sharp} \operatorname{Rem}(\langle (x - 1, y - 1) \rangle, x - y))$  $\operatorname{Rem}(f, p)$ : Graded reverse lexicographical order

$$= \left\langle x^2 - xy, xy - y^2 - 2x + 2y \right\rangle \sqcap^{\sharp} \left\langle y - 1 \right\rangle$$

$$=\left\langle x^{2}-xy,xy-y^{2}-2x+2y,y-1\right\rangle$$

**Concrete Domain**  $B^{\nu}[\![P]\!]\{(1,2)\}$ 

 $= (B^{\nu} \llbracket x := x + 1; \llbracket \{(1,2)\} \cap \llbracket x - y = 0 \rrbracket) \cup (B^{\nu} \llbracket y := x + 1; \llbracket \{(1,2)\} \cap \llbracket x - y \neq 0 \rrbracket)$ 

 $= \{(1,1)\}$ 

$$\gamma(\langle x-1, y-2 \rangle) = \{(1,2)\}$$

$$\gamma(\left\langle x^2 - xy, xy - y^2 - 2x + 2y, y - 1 \right\rangle) = \{($$

 $\gamma(\llbracket c \rrbracket^{\sharp} \langle g \rangle) \subseteq B^{\nu} \llbracket c \rrbracket \gamma(\langle g \rangle)$ 







### Correctness(Soundness)

### $\gamma(\llbracket c \rrbracket^{\sharp}\langle g \rangle) \subseteq B^{\nu}\llbracket c \rrbracket\gamma\langle g \rangle$

#### proved by structural induction with properties of ideals, and transfer lemma.

**Lemma 2** (Transfer lemma). Let  $(\mathcal{A}, \subseteq)$ ,  $(\mathcal{A}^{\sharp}, \subseteq^{\sharp})$  be two complete lattices and  $\gamma : \mathcal{A}^{\sharp} \to \mathcal{A}$  a function. Let  $f : \mathcal{A} \to \mathcal{A}$  and  $f^{\sharp} : \mathcal{A}^{\sharp} \to \mathcal{A}$  $\mathcal{A}^{\sharp}$  be two monotonic functions such that:

$$\gamma \circ f^{\sharp} \stackrel{.}{\subseteq} f \circ \gamma$$

Then we have:

 $\gamma(\nu f^{\sharp}) \subseteq \nu f$ 

**Theorem 3** (Correctness). Let g be a polynomial in  $\mathbb{R}[x_1, \ldots, x_m]$  and c be a polynomial program. Then:



### Correctness(Soundness)

# $\gamma(\llbracket c \rrbracket^{\sharp}\langle g \rangle) \subseteq B^{\nu}\llbracket c \rrbracket\gamma\langle g \rangle$

proved by structural induction with properties of ideals, and transfer lemma.

 $B^{\nu}[\![c]\!]\gamma(\langle g \rangle) = \mathbb{R}^m \implies g = 0$  is polynomial invariant ensure the Correctness of this work's method.

**Theorem 3** (Correctness). Let g be a polynomial in  $\mathbb{R}[x_1, \ldots, x_m]$  and c be a polynomial program. Then:





### Table of Contents

#### Motivation and Overview

#### **Semantics**

### **Fast inference of invariants**

- Complexity problem of ideal fixed point iteration
- Avoiding fixed-point iterations
- Algorithm, Benchmarks





## <u>Complexity problem of ideal fixed point iteration</u>

**[[while** p = 0 **do** c]]<sup> $\sharp$ </sup> $I = v(\overline{F}_{c,p,I}^{\sharp})$ 

where  $\overline{F}_{c,p,I}^{\sharp} = \lambda J \cdot p \cdot I \square^{\sharp} \operatorname{Rem}(\llbracket c \rrbracket^{\sharp} J, p)$ 

Computing in Ideal Domain ensure

the termination of ascending chain  $\langle 0 \rangle \subseteq \overline{I}$ but its iteration number upper bound

$$\nu(\overline{F}_{c,p,I}^{\sharp}) = \bigcup_{n} (\overline{F}_{c,p,I}^{\sharp})^{n}(\langle 0 \rangle)$$

$$\overline{F}_{c,p,I}^{\sharp}(\langle 0 \rangle) \subseteq (\overline{F}_{c,p,I}^{\sharp})^{2}(\langle 0 \rangle) \subseteq \cdots$$
  
I is unknown.

(by ordinary inclusion order)





## Complexity problem of ideal fixed point iteration

**[[while** p = 0 do c]]<sup> $\sharp$ </sup> $I = v(\overline{F}_{c,p,I}^{\sharp})$ 

where  $\overline{F}_{c,p,I}^{\sharp} = \lambda J. p \cdot I \sqcap^{\sharp} \operatorname{Rem}(\llbracket c \rrbracket^{\sharp} J, p)$ 

Computing in Ideal Domain ensure

the termination of ascending chain  $\langle 0 \rangle \subseteq F$ but its iteration number upper bound

Moreover, Gröbner bases computation, which is necessary to decide the termination of Kleene Iteration, is **EXP-SPACE complete**[W. Mayr, 1996]  $\overline{F}_{c.p.I}^{\sharp}(\langle 0 \rangle)^n \supseteq (\overline{F}_{c.p.I}^{\sharp})^{n+1}(\langle 0 \rangle)$ 

$$\nu(\overline{F}_{c,p,I}^{\sharp}) = \bigcup_{n} (\overline{F}_{c,p,I}^{\sharp})^{n} (\langle 0 \rangle)$$

$$\overline{F}_{c,p,I}^{\sharp}(\langle 0 \rangle) \subseteq (\overline{F}_{c,p,I}^{\sharp})^{2}(\langle 0 \rangle) \subseteq \cdots$$
  
**is unknown**.





## Complexity problem of ideal fixed point iteration

**[[while** p = 0 do c]]<sup> $\sharp$ </sup> $I = v(\overline{F}_{c,p,I}^{\sharp})$ 

where  $\overline{F}_{c,p,I}^{\sharp} = \lambda J. p \cdot I \sqcap^{\sharp} \operatorname{Rem}(\llbracket c \rrbracket^{\sharp} J, p)$ 

Computing in Ideal Domain ensure

the termination of ascending chain  $\langle 0 \rangle \subseteq F$ but its iteration number upper bound

Moreover, Gröbner bases computation, which is necessary to decide the termination of Kleene Iteration, is **EXP-SPACE complete**[W. Mayr, 1996]  $\overline{F}_{c.p.I}^{\sharp}(\langle 0 \rangle)^n \supseteq (\overline{F}_{c.p.I}^{\sharp})^{n+1}(\langle 0 \rangle)$ 

 $\rightarrow$  This work try to **inference** a part of **polynomial invariants**  $\approx$  narrow the search space and shorten the computation

$$\nu(\overline{F}_{c,p,I}^{\sharp}) = \bigcup_{n} (\overline{F}_{c,p,I}^{\sharp})^{n} (\langle 0 \rangle)$$

$$\overline{F}_{c,p,I}^{\sharp}(\langle 0 \rangle) \subseteq (\overline{F}_{c,p,I}^{\sharp})^{2}(\langle 0 \rangle) \subseteq \cdots$$
  
**I is unknown**.





## Avoiding fixed point iteration

**[[while** 
$$p \neq 0$$
 **do**  $c$ ]] <sup>$\sharp$</sup>  $I = v(F_{c,p,I}^{\sharp})$   
where  $F_{c,p,I}^{\sharp} = \lambda J. p \cdot ([[c]]^{\sharp}J) \sqcap^{\sharp} \operatorname{Rem}(I, p)$   
**where**  $\overline{F}_{c,p,I}^{\sharp} = \lambda J. p \cdot I \sqcap^{\sharp} \operatorname{Rem}([[c]]^{\sharp}J, p)$   
dea: Focus on loop invariants by a constraint  $[[c]]^{\sharp}I \equiv I$   
equality of  $\mathbb{R}^m$  zeros of polynomial  
compute constraints for loop invariants together with loop comparison

ld

 $\rightarrow$  Compute constraints for loop invariants together with loop semantics







## Avoiding fixed point iteration

$$\llbracket \mathbf{while} \ p \neq 0 \ \mathbf{do} \ c \rrbracket^{\sharp} I = \nu(F_{c,p,I}^{\sharp}) \qquad \llbracket \mathbf{v}$$

where  $F_{c,p,I}^{\sharp} = \lambda J. p \cdot (\llbracket c \rrbracket^{\sharp} J) \sqcap^{\sharp} \operatorname{Rem}(I, p)$ 

Idea: Focus on loop invariants by a constraint  $[\![c]\!]^{\sharp}I \equiv I$ 

 $\rightarrow$  Compute **constraints for loop invariants** together with loop semantics

Correctness for dis-equality guards is given as follows

!! Correctness for equality guards is not given in this work. !!

- while p = 0 do  $c]]^{\sharp}I = v(\overline{F}_{c,p,I}^{\sharp})$
- where  $\overline{F}_{c,p,I}^{\sharp} = \lambda J. p \cdot I \sqcap^{\sharp} \operatorname{Rem}(\llbracket c \rrbracket^{\sharp} J, p)$

- **Theorem 5.** Let  $I \in \mathcal{I}$  and  $w \equiv while p \neq 0$  do c be a polynomial program. Suppose that  $[c]^{\sharp}I = I$ . Then  $[w]^{\sharp}I = I$ .



### Refined Semantics for fast inferece

Refined Semantics without fixed point computation

 $[\mathbf{x}_i := p]^{\sharp_{\mathcal{C}}}(I, \mathcal{C}) = (\langle \{q[x_i \mapsto p], q \in I\} \rangle, \mathcal{C})$  $\llbracket \mathbf{skip} \rrbracket^{\sharp_{C}}(I, C) = (I, C)$  $[[s_1; s_2]]^{\sharp_{\mathcal{C}}}(I, C) = ([[s_1]]^{\sharp_{\mathcal{C}}}([[s_2]]^{\sharp_{\mathcal{C}}}(I, C)))$  $\llbracket \text{if } p \neq 0 \text{ then } c_1 \text{ else } c_2 \rrbracket^{\sharp_C}(I, C) = (p \cdot I_1 \sqcap^{\sharp} \operatorname{Rem}_{par}(I_2, p), C_1 \cup C_2)$  $\llbracket if p = 0$  then  $c_1$  else  $c_2 \rrbracket^{\sharp c}(I, C) = (p \cdot I_2 \sqcap^{\sharp} \operatorname{Rem}_{par}(I_1, p), C_1 \cup C_2)$ where  $[c_1]^{\sharp_{C}}(I, C) = (I_1, C_1)$ and  $[c_2]^{\sharp c}(I, C) = (I_2, C_2)$ [while  $p \bowtie 0$  do c]<sup> $\sharp c$ </sup> $(I, C) = (I, C' \cup C_w)$ where  $[c_1]^{\sharp c}(I, C) = (I', C')$ and  $C_w = \{I \equiv I'\}$ 

 $\llbracket c \rrbracket^{\sharp_{c}} : \mathcal{I}_{par} \times \mathcal{C} \to \mathcal{I}_{par} \times \mathcal{C}$ 

**Parametrized Ideals and Constraints w.r.t parameters** 





### Refined Semantics for fast inferece

Refined Semantics without fixed point computation

 $[\![\mathbf{x}_i := p]\!]^{\sharp_{\mathcal{C}}}(I, C) = (\langle \{q[x_i \mapsto p], q \in I\} \rangle, C)$  $\llbracket \mathbf{skip} \rrbracket^{\sharp_{C}}(I, C) = (I, C)$  $[[s_1; s_2]]^{\sharp_{\mathcal{C}}}(I, C) = ([[s_1]]^{\sharp_{\mathcal{C}}}([[s_2]]^{\sharp_{\mathcal{C}}}(I, C)))$  $\llbracket \text{if } p \neq 0 \text{ then } c_1 \text{ else } c_2 \rrbracket^{\sharp_C}(I, C) = (p \cdot I_1 \sqcap^{\sharp} \operatorname{Rem}_{par}(I_2, p), C_1 \cup C_2)$  $\llbracket if p = 0$  then  $c_1$  else  $c_2 \rrbracket^{\sharp c}(I, C) = (p \cdot I_2 \sqcap^{\sharp} \operatorname{Rem}_{par}(I_1, p), C_1 \cup C_2)$ where  $[c_1]^{\sharp_{C}}(I, C) = (I_1, C_1)$ and  $[c_2]^{\sharp c}(I, C) = (I_2, C_2)$ [while  $p \bowtie 0$  do c]<sup> $\sharp c$ </sup> $(I, C) = (I, C' \cup C_w)$ where  $[c_1]^{\sharp_{C}}(I, C) = (I', C')$ and  $C_w = \{I \equiv I'\}$ 

 $\llbracket c \rrbracket^{\sharp_{c}} : \mathcal{I}_{par} \times \mathcal{C} \to \mathcal{I}_{par} \times \mathcal{C}$ 

**Parametrized Ideals and Constraints w.r.t parameters** 

Ignore while guards, and **impose constraints** which requires equality of pre and post loop ideals,  $[\![c]\!]^{\sharp}I\equiv I$ 







Input: program c, degree d,

Output: a set of polynomials  $\mathcal{G}$ ,

#### begin

g := the most generic  $a_i$ -polynomial of degree d; computing abstract semantics  $(I, C) = [\![c]\!]^{\sharp_C} \langle g \rangle;$ generating  $\mathscr{C}_{g,c}$ , the constraint  $C \cup (I \equiv \langle 0 \rangle)$ ; computing  $\mathscr{S}_{g,c}$ , set of solutions of  $\mathscr{C}_{g,c}$ ;  $\mathcal{G} :=$ 

end

- set of polynomials obtained by  $a_i$ -instantiating g by elements of  $\mathscr{S}_{g,c}$



Input: program c, degree d,

Output: a set of polynomials  $\mathcal{G}$ ,

#### begin

g := the most generic  $a_i$ -polynomial of degree d; Monomial numbers are  $_{n}H_{d}$ computing abstract semantics  $(I, C) = [\![c]\!]^{\sharp_C} \langle g \rangle;$ where *n* is number of program variables generating  $\mathscr{C}_{g,c}$ , the constraint  $C \cup (I \equiv \langle 0 \rangle)$ ; computing  $\mathscr{S}_{g,c}$ , set of solutions of  $\mathscr{C}_{g,c}$ ;  $\mathcal{G} :=$ 

set of polynomials obtained by  $a_i$ -instantiating g by elements of  $\mathscr{S}_{g,c}$ end

### Algorithm

#### Example of most generic template of degree 3, with program variables x, y, z

 $a_{17}x^3 + a_{16}x^2y + a_{15}xy^2 + a_{14}y^3 + a_{13}x^2z + a_{12}y^2z + a_{11}xz^2 + a_{10}yz^2 + a_{9}z^3 + a_{8}x^2 + a_{7}xy$  $+a_6y^2 + a_5xz + a_4z^2 + a_3x + a_2y + a_1z + a_0$ 







#### $c := x = 0; i = 0; while(i != n) \{x = x + i; i = i + 1; \}$

$$x=rac{1}{2}n^2-n, x=rac{1}{2}i^2-i$$
 are post

### Example

conditions, former is not loop invariant.





 $c := x = 0; i = 0; while(i != n) \{x = x + i; i = i + 1; \}$  $g := a_9 x^2 + a_8 x i + a_7 i^2 + a_6 x n + a_5 i n + a_4 n^2 + a_3 x + a_2 i + a_1 n + a_0$  $\llbracket c \rrbracket^{\sharp c}(\langle g \rangle, \emptyset)$  $= [ [x = 0; i = 0; ]]^{\sharp c}(\langle g \rangle, \{g \equiv h\})$ h := a $(a_2 +$  $= \left( \left\langle a_4 n^2 + a_1 n + a_0 \right\rangle, \left\{ \left\langle g \right\rangle \equiv \left\langle h \right\rangle \right\} \right)$ If we assume  $a_0 = 0$ correspondence of all coefficients  $a_1 = 0$ (sufficient but not necessary).  $a_4 = 0$  $a_{5} = 0$  $\{\langle g \rangle \equiv \langle h \rangle, \langle a_4 n^2 + a_1 n + a_0 \rangle \equiv \langle 0 \rangle\} \iff$  $a_{6} = 0$  $a_{8} = 0$  $a_{9} = 0$  $a_2 + a_7 = 0$  $a_3 + 2a_7 = 0$ 

### Example

$$a_9x^2 + (a_8 + 2a_9)xi + (a_7 + a_8 + a_9)i^2 + a_6xn + (a_5 + a_6)in + a_4n^2 + (a_3 + a_3 + 2a_7 + a_8)i + (a_1 + a_5)n + a_0 + a_2 + a_7$$

$$a_2 = t, a_3 = 2t, a_7 = -t$$

$$\Rightarrow \quad \forall t \in \mathbb{R} \ g = 2tx + ti - ti^2 = 0 \text{ is invariant.}$$





### Table of Contents

#### Kerview Motivation and Overview

#### Semantics

### Fast inference of invariants

#### **Related work**



### Related work

### Generalized Homogeneous Polynomials for Efficient Template-Based Nonlinear Invariant Synthesis[Kojima+. SAS16]

- Reduce number of monomials in generic templates by focusing on generalized homogeneous polynomials.
- Determine the Generalized degree of polynomials in programs by using Dimensional Type Inference.



41

#### Frequencies and Recurrences: Better Together[Breck+. POPL20]

#### Compute non-linear inequality invariants for Non-linearly recursive programs.

```
Input:
                C programs
int subsetSumAux(int * A, int i, int n, int sum) {
   nTicks++;
   if (i \ge n) {
                                                          nTicks' \le nTicks +
      if (sum == 0) { found = true; }
      return 0;
                                                                  h \leq \max(1, 1)
   int size = subsetSumAux(A, i + 1, n, sum + A[i]);
   if (found) { return size + 1; }
   size = subsetSumAux(A, i + 1, n, sum);
   return size;
```

### Related work

Output:

Non-linear inequality invariants.

$$2^{h} - 1 \land \text{return}' \leq h - 1 \land + n - i$$

Benchmark	Actual	CHORA	ICRA	Other Tools
fibonacci	$O(\varphi^n)$	$O(2^n)$	n.b.	$[2]:O(2^n)$
hanoi	$O(2^n)$	$O(2^n)$	n.b.	$[2]:O(2^n)$
subset_sum	$O(2^n)$	$O(2^n)$	n.b.	$[20]:O(2^n)$
bst_copy	$O(2^n)$	$O(2^n)$	n.b.	$[2]:O(2^n)$
ball_bins3	$O(3^n)$	$O(3^n)$	n.b.	$[20]:O(3^n)$
karatsuba	$O(n^{\log_2{(3)}})$	$O(n^{\log_2(3)})$	n.b.	[9]: $O(n^{1.6})$
mergesort	$O(n\log(n))$	$O(n\log(n))$	n.b.	$[2]:O(n\log(n))$
strassen	$O(n^{\log_2(7)})$	$O(n^{\log_2(7)})$	n.b.	$[9]:O(n^{2.9})$
qsort_calls	O(n)	$O(2^n)$	O(n)	[8]:O(n)
qsort_steps	$O(n^2)$	$O(n2^n)$	n.b.	$[9]:O(n^2)$
closest_pair	$O(n\log(n))$	n.b.	n.b.	$[9]:O(n\log(n))$
ackermann	Ack(n)	n.b.	n.b.	[2]:n.b.



### Polynomial Invariant Generation for Non-deterministic Recursive Programs[Chatterjee+. PLDI20]

- for non-linearly recursive C programs.
- Sub-exponential time complexity.

Presents semi-complete polynomial inequality invariants generation method



43

- Killer-Olm and Seidl (2002). Polynomial Constants Are decidable
- Kenneration Stream and Sipma, Henny B. and Manna, Zohar (2004). Non-linear loop invariant generation using Gröbner bases.
- Kervice Representation Herview Representation Herview Representation Herview Representation Representatio Representatio Representation Representatio Representation Represe
- Example 2004). Automatically Generating Loop Invariants Using
   Action
   Section: 
   Example 2004). Automatically Generating Loop Invariants
   Output
   Description: 
   Section: 
   Section: Quantifier Elimination – Preliminary Report–.
- Kight Glynn Winskel (1993). The Formal Semantics of Programming Languages: An Introduction

